# Digital Communication Systems ECS 452

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### 7. Additive Noise in the Waveform Channel



#### **Office Hours:**

BKD, 4th floor of Sirindhralai building

Monday Thursday Friday 14:00-16:00 10:30-11:30 12:00-13:00

## **Review:**

#### 11.5 Linear Dependence

**Definition 11.55.** Given two random variables X and Y, we may calculate the following quantities:

(a) Correlation:  $\mathbb{E}[XY]$ . (b) Covariance:  $\operatorname{Cov}[X,Y] = \mathbb{E}[(X - \mathbb{E}X)(Y - \mathbb{E}Y)]$ . (c) Correlation coefficient:  $\rho_{X,Y} = \frac{\operatorname{Cov}[X,Y]}{\sigma_X \sigma_Y} = \mathbb{E}\left[\left(\frac{\times -\mathbb{E}\times}{\sigma_X}\right)\left(\frac{\vee -\mathbb{E}\times}{\sigma_Y}\right)\right]$ 

#### ECS 315: Probability and Random Processes HW Solution 10 — Due: Nov 18, 8:59 AM

Lecturer: Prapun Suksompong, Ph.D.

**Problem 1** (Randomly Phased Sinusoid). Suppose  $\Theta$  is a uniform random variable on the interval  $(0, 2\pi)$ .

(a) Consider another random variable X defined by

 $X = 5\cos(7t + \Theta)$ 

where t is some constant. Find  $\mathbb{E}[X]$ .

(b) Consider another random variable Y defined by

 $Y = 5\cos(7t_1 + \Theta) \times 5\cos(7t_2 + \Theta)$ 

where  $t_1$  and  $t_2$  are some constants. Find  $\mathbb{E}[Y]$ .

2015/1

# **Conversion to Vector Channels**

**Waveform Channel**: R(t) = S(t) + N(t)

**Vector Channel** 

 $\vec{R} = \vec{S} + \vec{N}$ 

Note that  $S_j^{(i)}$ , the  $j^{\text{th}}$  component of the  $\overrightarrow{S}$  vector, comes from the inner-product:

 $S_{j}^{(i)} = \left\langle S(t), \phi_{j}(t) \right\rangle$ 

The received vector  $\vec{R}$  is computed in the same way: the *j* component is given by

 $R_{j} = \left\langle r(t), \phi_{j}(t) \right\rangle$ 

 $N_i = \langle N(t), \phi_i(t) \rangle$ 

In which case, the corresponding noise vector  $\overline{N}$  is computed in the same way: the *j* component is given by

Ν

Use GSOP to find *K* orthonormal basis functions  $\{\phi_1(t), \phi_2(t), \dots, \phi_K(t)\}$ for the space spanned by  $\{s_1(t), s_2(t), \dots, s_M(t)\}$ . This gives vector representations for the waveforms  $s_1(t), s_2(t), \dots, s_M(t)$ :

 $\overline{S}^{(1)}, \overline{S}^{(2)}, \dots, \overline{S}^{(M)}$ 

which can be visualized in the form of signal constellation

Prior Probabilities:

$$p_{i} = P[W = i] = P[S(t) = s_{i}(t)]$$
$$= P[\vec{S} = \vec{s}^{(i)}]$$

For additive white **Gaussian** noise (AWGN) process N(t),

$$_{i} \sim N \sim \mathcal{N}\left(0, \frac{N_{0}}{2}\right) = \mathcal{N}\left(0, \sigma^{2}\right) \Longrightarrow \bar{N} \sim \mathcal{N}\left(\bar{0}, \frac{N_{0}}{2}I\right) \Longrightarrow f_{\bar{N}}\left(\bar{n}\right) = \frac{1}{\left(2\pi\right)^{\frac{K}{2}}\sigma^{K}} e^{\frac{-\frac{1\|\bar{n}\|^{2}}{2\sigma^{2}}}$$